



A. JAMES CLARK
SCHOOL OF ENGINEERING

The
Institute for
Systems
Research

Fundamental limits of feedback: an information theoretic viewpoint

Basic results and definitions of information theory

Nuno C. Martins

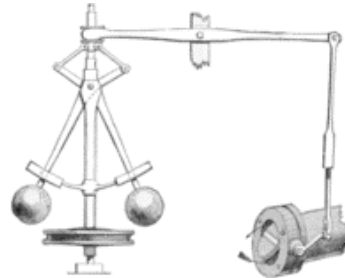
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Tomorrow's talk will focus on



H. W. Bode

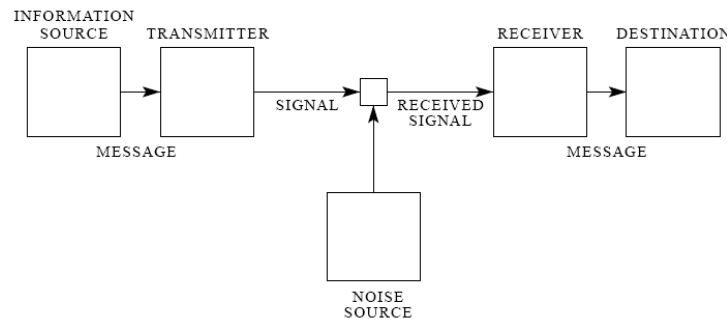


*Linear Time-Invariant
Feedback Systems*

Sensitivity to external
excitation



C. Shannon



Maximum rate of
reliable information
transfer

(Extracted from: A Mathematical Theory of Communication)

Information Theory Basic Quantities

Entropy

Consider a random variable $\mathbf{z}$ with alphabet $\mathbf{Z} = \{1, \dots, M\}$

There is a representation where we assign $\lceil -\log p_z(z) \rceil$ bits to each z and the expected size becomes:

$$E[\lceil -\log p_z(\mathbf{z}) \rceil]$$

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Entropy is the expected size of the most bit-economic representation:



$$H(\mathbf{z}) = E[-\log p_z(\mathbf{z})]$$

(valid on average for a large collection of variables)

Information Theory Basic Quantities

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$$H(\mathbf{z}) = - \sum_{z \in \mathbf{Z}} p_z(z) \log p_z(z)$$

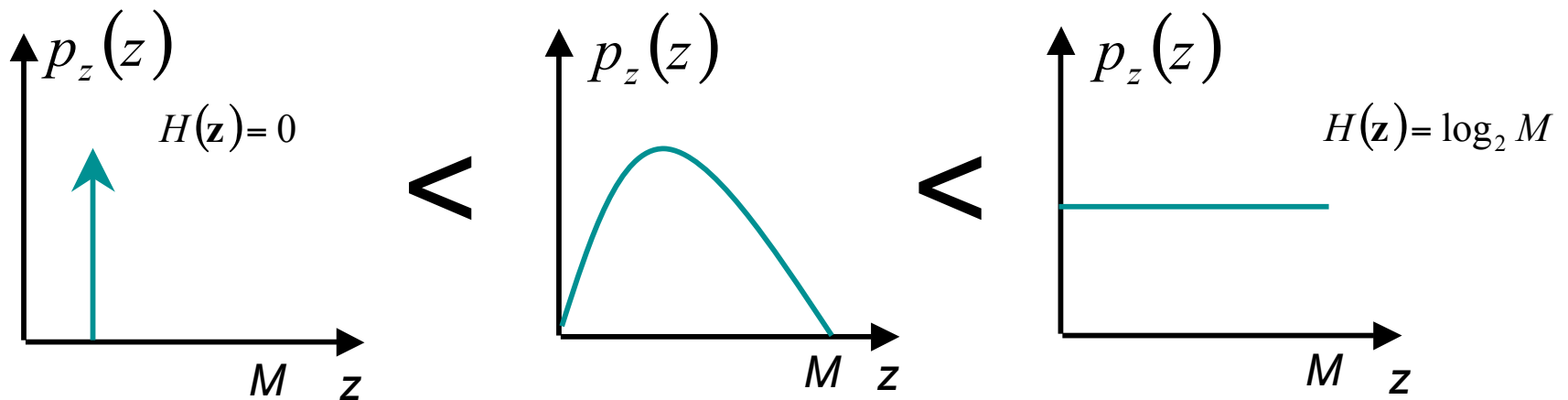
Information Theory Basic Quantities

Properties of Entropy:

$$H(\mathbf{z}) \geq 0$$

$\mathbf{z}$ can be represented as $2^{H(\mathbf{z})}$ uniformly distributed binary random variables

Measure of randomness

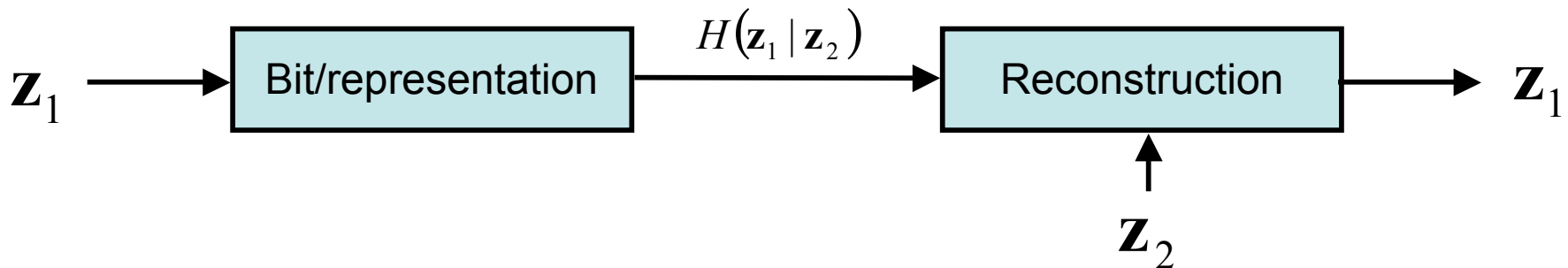


Information Theory Basic Quantities

Properties of Entropy:

Conditional Entropy

$$H(\mathbf{z}_1 | \mathbf{z}_2) = H(\mathbf{z}_1, \mathbf{z}_2) - H(\mathbf{z}_2) = E[-\log p_{\mathbf{z}_1|\mathbf{z}_2}(\mathbf{z}_1 | \mathbf{z}_2)]$$

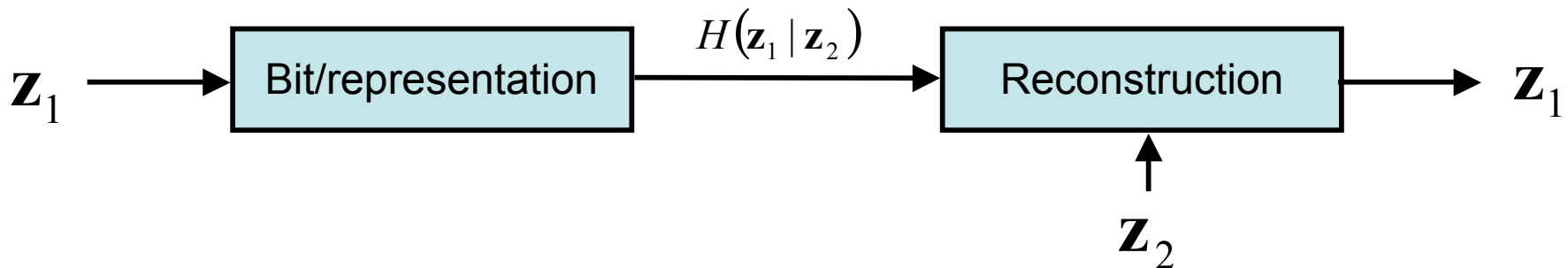


Information Theory Basic Quantities

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How much information does $\mathbf{z}_2$ carry about $\mathbf{z}_1$?

$$I(\mathbf{z}_1, \mathbf{z}_2) = H(\mathbf{z}_1) - H(\mathbf{z}_1 | \mathbf{z}_2)$$

Information Theory Basic Quantities

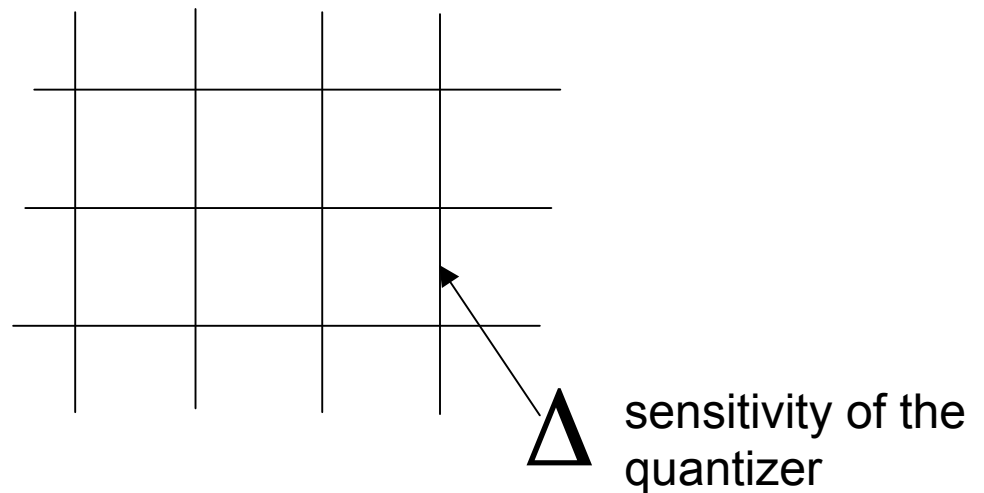
“Continuous” random variables

Assume that $\mathbf{w}$ is a random variable with alphabet $\mathcal{W} = \mathfrak{R}^n$

Differential entropy or “entropy density”:

$$\underbrace{2^{h(\mathbf{w})}}_{\text{unif. dist. volume}} = \lim_{\Delta \rightarrow 0} \left[\underbrace{\Delta}_{\text{This many elements unif. dist.}} 2^{H(f_{\Delta}(\mathbf{w}))} \right]$$

f_{Δ} is a quantizer



Information Theory Basic Quantities

“Continuous” random variables

$$I(\mathbf{w}_1, \mathbf{w}_2) \stackrel{def}{=} \lim_{\Delta \rightarrow 0} I(f_{\Delta}(\mathbf{w}_1), f_{\Delta}(\mathbf{w}_2)) = h(\mathbf{w}_1) - h(\mathbf{w}_1 | \mathbf{w}_2)$$

The function of the quantizer is to extract as “much” information as possible from the continuous random variables.

Information Theory Basic Quantities

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“Continuous” and discrete random variables

$$I(\mathbf{z}, \mathbf{w}) = \lim_{\Delta \rightarrow 0} I(f_{\Delta}(\mathbf{z}), \mathbf{w}) = h(\mathbf{z}) - h(\mathbf{z} | \mathbf{w})$$

Information Theory Basic Quantities

Properties:

I (Positivity)

$$I(\mathbf{w}, \mathbf{z}) = I(\mathbf{z}, \mathbf{w}) \geq 0$$

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II (Kolmogorov's Formula)

Given $\mathbf{v}$, how much more information about $\mathbf{z}$ can I get from $\mathbf{w}$?

$$I(\mathbf{w}, \mathbf{z} | \mathbf{v}) = I((\mathbf{w}, \mathbf{v}), \mathbf{z}) - I(\mathbf{v}, \mathbf{z}) = h(\mathbf{z} | \mathbf{v}) - h(\mathbf{z} | \mathbf{w}, \mathbf{v})$$

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III (maximum entropy bounds)

$$H(\mathbf{a}) \leq \log(\# \mathbf{A})$$

$$h(\mathbf{z}^k) \leq \frac{1}{2} \log \left((2\pi e)^k |\Sigma_{\mathbf{z}^k}| \right) \leq \frac{1}{2} \sum_{i=1}^k \log(2\pi e \sigma_{z(i)}^2)$$

Equality is achieved if $\mathbf{z}^k$ is Gaussian

Equality is achieved if $z(i)$ are uncorrelated

Information Theory Basic Quantities

Important Aspects about (differential) entropy and Mutual Information

Equality if g is
injective

$$\longrightarrow h(a | b) \leq h(a - f \circ g(b) | g(b))$$

Cannot Reduce
Uncertainty without
more information

Equality under
Invertible f and g

$$\longrightarrow I(a, b) \geq I(g(a), f(b))$$

data processing inequality

Limit on the ability
To send Information

$$h(a - f \circ g(b) | g(b)) \geq h(a) - I(a, b)$$

Limit on the ability
to reduce
uncertainty

Information Theory Basic Quantities

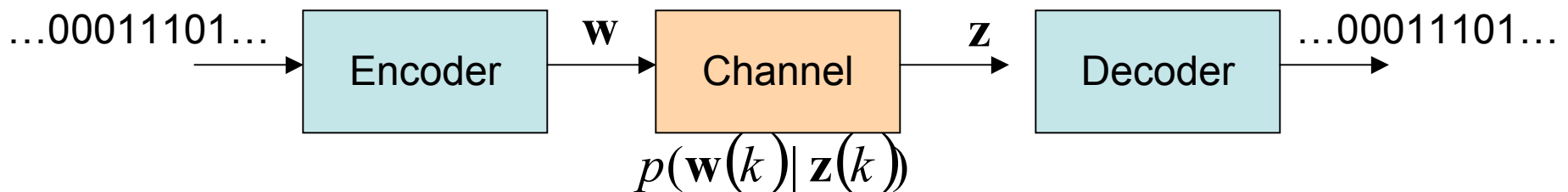
Definition in terms of rates:

Consider two “continuous” or discrete stochastic processes:

$$\mathbf{w}^k = (\mathbf{w}(0), \dots, \mathbf{w}(k))$$

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(Information rate)
$$I_\infty(\mathbf{w}, \mathbf{z}) = \lim_{k \rightarrow \infty} \frac{I(\mathbf{z}^k, \mathbf{w}^k)}{k}$$
 Maximum reliable bit-rate.

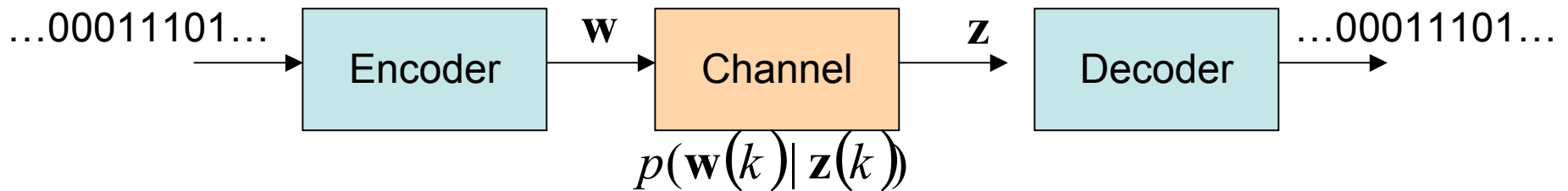


(Channel coding Theorem)

Channel Coding Theorem

Channel Capacity

(Information rate) $I_\infty(\mathbf{w}, \mathbf{z}) = \lim_{k \rightarrow \infty} \frac{I(\mathbf{z}^k, \mathbf{w}^k)}{k}$ Rate of reliable transmission



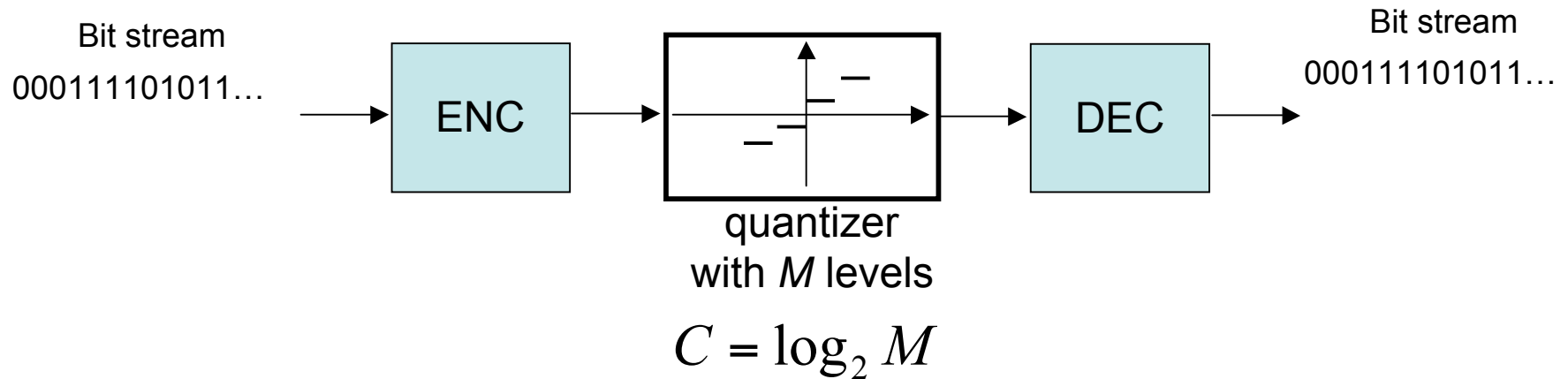
(Channel coding Theorem)

Given a (constrained) set of stochastic processes $S_{\mathbf{w}}$, channel capacity is given by:

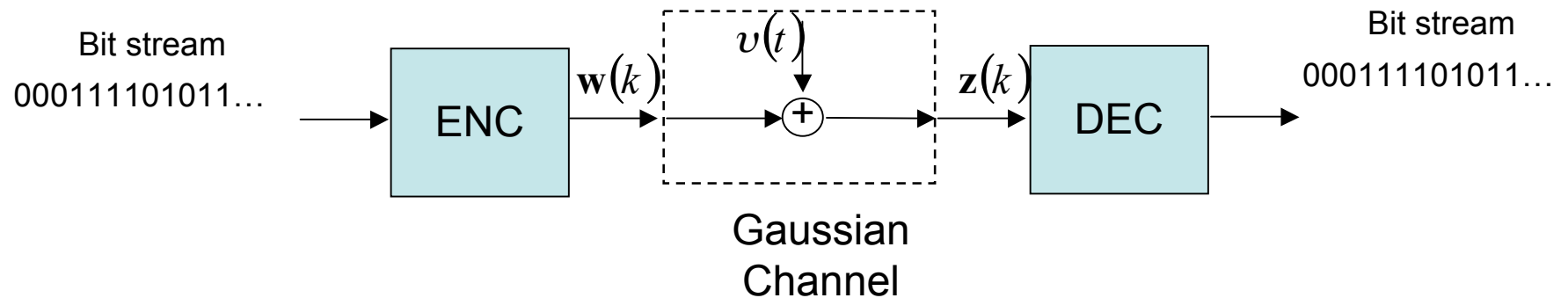
$$C = \sup_{\mathbf{w} \in S_{\mathbf{w}}} \lim_{k \rightarrow \infty} \frac{I(\mathbf{z}^k, \mathbf{w}^k)}{k} = \sup_{p_{\mathbf{w}(k)} \text{ memoryless}} I(\mathbf{z}(k), \mathbf{w}(k))$$

Channel Coding Theorem

Examples: Quantizer with M levels



Examples: Gaussian channel



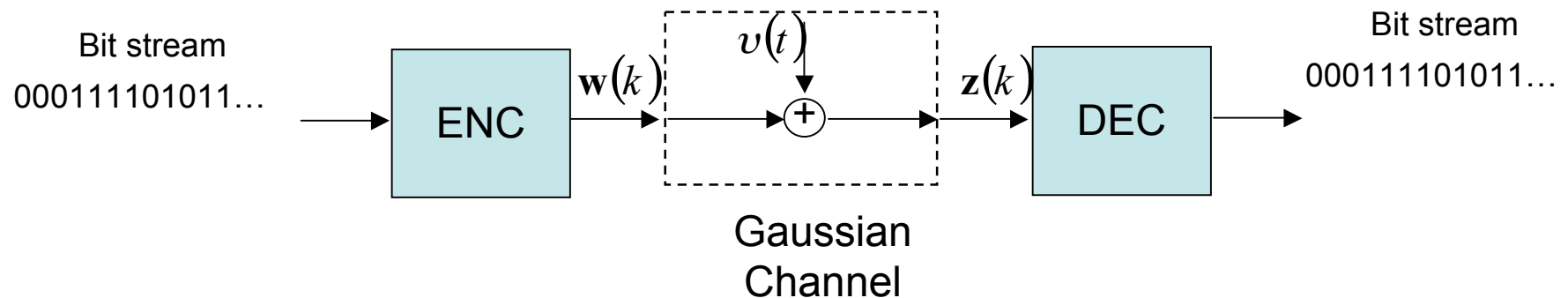
$$C = \frac{1}{2} \log_2 \left(1 + \frac{\sigma_w^2}{\sigma_v^2} \right) \leftarrow \text{Shannon Capacity}$$



Channel Coding Theorem

Examples: Gaussian channel in more detail

Information capacity is the **supremum** of the bit-rate for which information can be transmitted through a medium:



If $N(k)$ represents the total number of bits transmitted up to time k then we know that

$$\begin{cases} \sup_k \frac{N(k)}{k} \leq \frac{1}{2} \log_2 \left(1 + \frac{\sigma_w^2}{\sigma_v^2} \right) \\ P[Error(k)] \rightarrow 0 \end{cases} \leftarrow \text{Shannon Capacity}$$



Rates and bounds

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(Information rate)
$$I_{\infty}(\mathbf{w}, \mathbf{z}) = \lim_{k \rightarrow \infty} \frac{I(\mathbf{z}^k, \mathbf{w}^k)}{k}$$

Maximum reliable bit-rate: used to define capacity.

(Entropy rate)
$$h_{\infty}(\mathbf{z}) = \lim_{k \rightarrow \infty} \frac{h(\mathbf{z}^k)}{k}$$

$$h_{\infty}(\mathbf{z}) \leq \frac{1}{4\pi} \int_{-\pi}^{\pi} \log(2\pi e F_z(\omega)) d\omega$$

Equality is achieved if $\mathbf{z}$ is Gaussian

Example of application

Consider the following scalar linear and time-invariant system:

$$\mathbf{x}(k+1) = a\mathbf{x}(k) + \mathbf{u}(k) \quad k \geq 0 \quad |a| > 1$$

$\mathbf{x}(0)$ is a random variable uniformly distributed in the interval $[-1, 1]$

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$\mathbf{x}(0)$ is a random variable uniformly distributed in the interval $[-1, 1]$

We will prove that:

$$\sup_k E[\mathbf{x}^2(k)] < \beta \quad \Rightarrow \quad \lim_{k \rightarrow \infty} \frac{I(\mathbf{u}^k, \mathbf{x}(0))}{k} \geq \log|a|$$

Example of application

Proof:

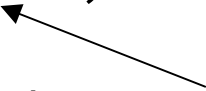
$$\mathbf{x}(k+1) = a\mathbf{x}(k) + \mathbf{u}(k)$$

The state can be computed as:

$$\mathbf{x}(k) = a^k \mathbf{x}(0) + f(k, \mathbf{u}^k)$$

$$a^{-k} \mathbf{x}(k) = \mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k) \quad \tilde{f}(k, \mathbf{u}^k) = -a^{-k} f(k, \mathbf{u}^k)$$

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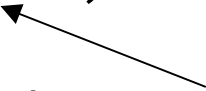
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Now, using the formula for mutual information:

$$I(\mathbf{x}(0), \tilde{f}(k, \mathbf{u}^k)) = h(\mathbf{x}(0)) - h(\mathbf{x}(0) | \tilde{f}(k, \mathbf{u}^k))$$

$$I(\mathbf{x}(0), \tilde{f}(k, \mathbf{u}^k)) = 2 - h(\mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k) | \tilde{f}(k, \mathbf{u}^k)) \geq 2 - h(\mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k))$$

Example of application

Proof (Continuation):

$$a^{-k} \mathbf{x}(k) = \mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k) \quad \sup_k E[\mathbf{x}^2(k)] < \beta$$

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Now notice that:

$$h(\mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k)) \leq \frac{1}{2} \log \left(2\pi e E[\mathbf{x}(0) - \tilde{f}(k, \mathbf{u}^k)] \right) \leq \frac{1}{2} \log(2\pi e a^{-2k} \beta)$$

Example of application

Proof (Continuation):

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Proof (Continuation):

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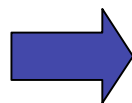
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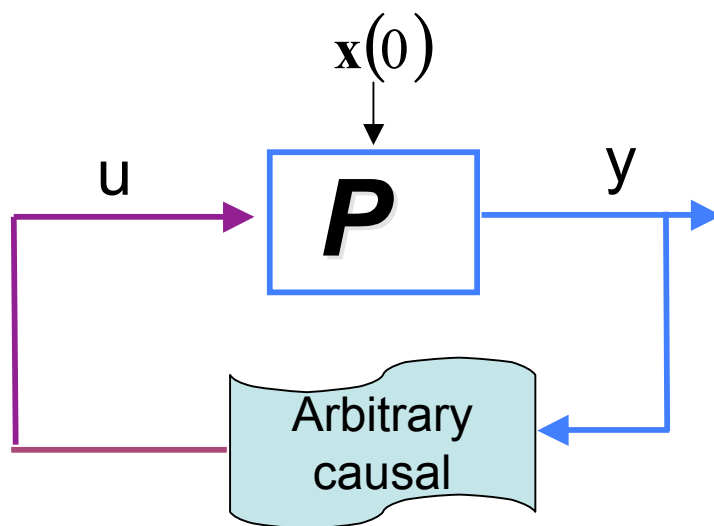
data processing inequality:



$$\lim_{k \rightarrow \infty} \frac{I(\mathbf{x}(0), \mathbf{u}^k)}{k} \geq \log|a|$$

Example of application

The previous analysis leads to an alternative proof for the following result of Tatikona and Mitter (00):



If the feedback interconnection is second moment stable then:

$$\lim_{k \rightarrow \infty} \frac{I(\mathbf{x}(0), \mathbf{u}^k)}{k} \geq \sum_{unstable} \log |pole_i|$$